CS 1550 Introduction to Operating Systems

RECITATION – WEEK 9

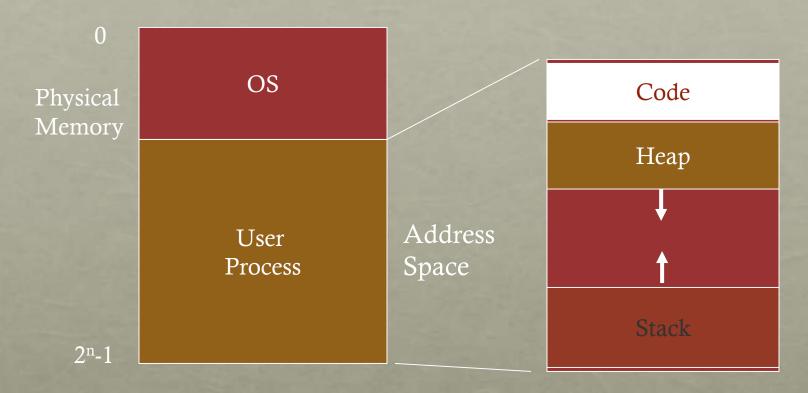
Pranut Jain

DISCLAIMER

• Slides originally by Andrea for Dr. Remzi H. Arpaci-Dusseau, UNIVERSITY of WISCONSIN-MADISON

MOTIVATION FOR VIRTUALIZATION

Uniprogramming: One process runs at a time



Disadvantages:

- Only one process runs at a time
- Process can destroy OS

MULTIPROGRAMMING GOALS

Transparency

- Processes are not aware that memory is shared
- Works regardless of number and/or location of processes

Protection

- Cannot corrupt OS or other processes
- Privacy: Cannot read data of other processes

Efficiency

Do not waste memory resources (minimize fragmentation)

Sharing

Cooperating processes can share portions of address space

ABSTRACTION: ADDRESS SPACE

Address space: Each process has set of addresses that map to bytes

Problem:

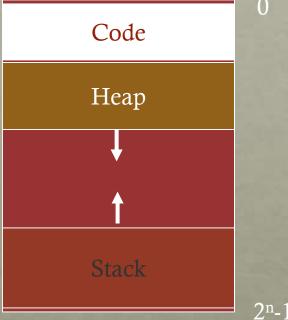
How can OS provide illusion of private address space to each process?

Review: What is in an address space?

Address space has static and dynamic components

Static: Code and some global variables

Dynamic: Stack and Heap



MOTIVATION FOR DYNAMIC MEMORY

Why do processes need dynamic allocation of memory?

- Do not know amount of memory needed at compile time
- Must be pessimistic when allocate memory statically
 - Allocate enough for worst possible case; Storage is used inefficiently

Recursive procedures

Do not know how many times procedure will be nested

Complex data structures: lists and trees

```
struct my_t *p = (struct my_t *)malloc(sizeof(struct my_t));
```

Two types of dynamic allocation

- Stack
- Heap

STACK ORGANIZATION

Definition: Memory is freed in opposite order from allocation

```
alloc(A);
alloc(B);
alloc(C);
free(C);
alloc(D);
free(D);
free(B);
```

Simple and efficient implementation: Pointer separates allocated and freed space

Allocate: Increment pointer

Free: Decrement pointer

No fragmentation

WHERE ARE STACKS USED?

OS uses stack for procedure call frames (local variables and parameters)

```
main () {
    int A = 0;
    foo (A);
    printf("A: %d\n", A);
}

void foo (int Z) {
    int A = 2;
    Z = 5;
    printf("A: %d Z: %d\n", A, Z);
}
```

HEAP ORGANIZATION

Definition: Allocate from any random location: malloc(), new()

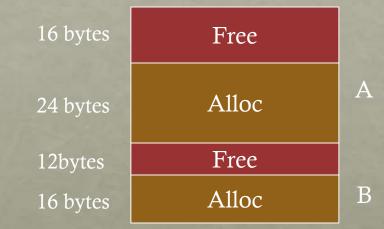
- Heap memory consists of allocated areas and free areas (holes)
- Order of allocation and free is unpredictable

Advantage

Works for all data structures

Disadvantages

- Allocation can be slow
- End up with small chunks of free space fragmentation
- Where to allocate 12 bytes? 16 bytes? 24 bytes??
- What is OS's role in managing heap?
 - OS gives big chunk of free memory to process; library manages individual allocations



QUIZ: MATCH THAT ADDRESS LOCATION

```
int x;
int main(int argc, char *argv[]) {
  int y;
  int *z = malloc(sizeof(int)););
}
```

Possible segments: static data, code, stack, heap

What if no static data segment?

Address	Location
X	Static data → Code
main	Code
у	Stack
z	Stack
*Z	Неар

MEMORY ACCESSES

```
#include <stdio.h>
#include <stdlib.h>

int main(int argc, char *argv[]) {
  int x;
  x = x + 3;
}
```

0x10: movl0x8(%rbp), %edi

0x13: addl \$0x3, %edi

0x19: movl%edi, 0x8(%rbp)

otool -tv demo1.o (or objdump on Linux)

%rbp is the base pointer: points to base of current stack frame

QUIZ: MEMORY ACCESSES?

Initial %rip = 0x10%rbp = 0x200



0x10: movl0x8(%rbp), %edi

0x13: addl \$0x3, %edi

0x19: movl%edi, 0x8(%rbp)

%**rbp** is the base pointer: points to base of current stack frame

%rip is instruction pointer (or program counter)

Memory Accesses to what addresses?

Fetch instruction at addr 0x10 Exec:

load from addr 0x208

Fetch instruction at addr 0x13 Exec:

no memory access

Fetch instruction at addr 0x19 Exec:

store to addr 0x208

HOW TO VIRTUALIZE MEMORY?

Problem: How to run multiple processes simultaneously?

Addresses are "hardcoded" into process binaries

How to avoid collisions?

Possible Solutions for Mechanisms (covered today):

- 1. Time Sharing
- 2. Static Relocation
- 3. Base
- 4. Base+Bounds
- 5. Segmentation

1) TIME SHARING OF MEMORY

Try similar approach to how OS virtualizes CPU

Observation:

OS gives illusion of many virtual CPUs by saving CPU registers to memory when a process isn't running

Could give illusion of many virtual memories by saving memory to disk when process isn't running

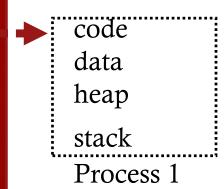
Memory code data Program

TIME SHARE MEMORY: EXAMPLE

code data Program

Memory

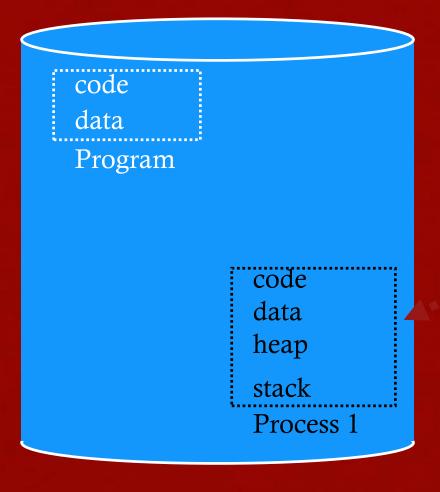
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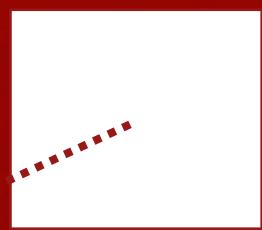


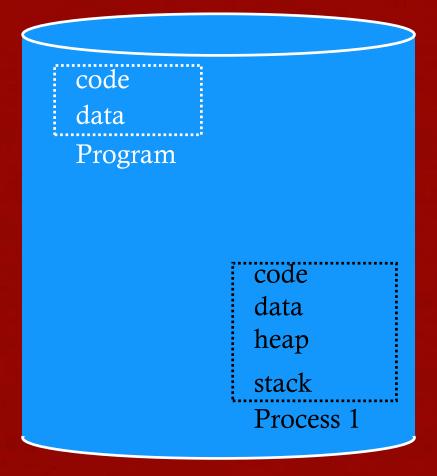
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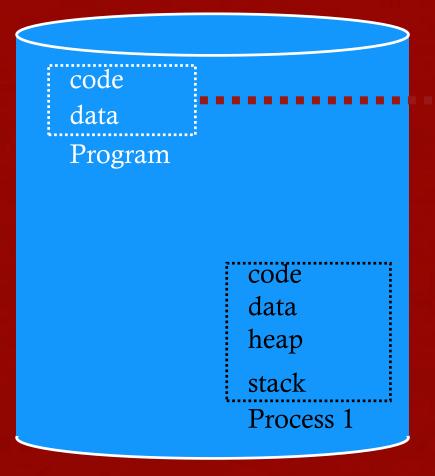
Memory

code
data
heap
stack
Process 1

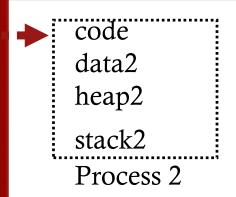








create



code data Program

> code data heap stack

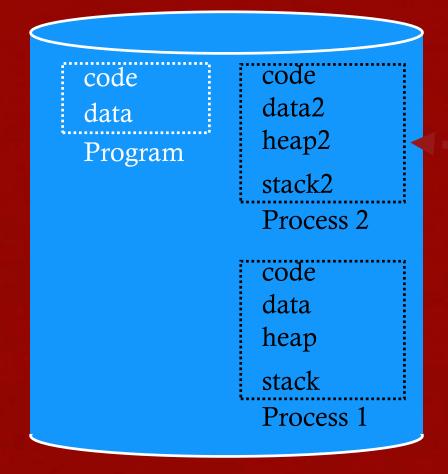
> > Process 1

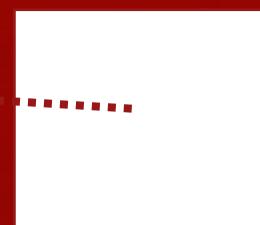
Memory

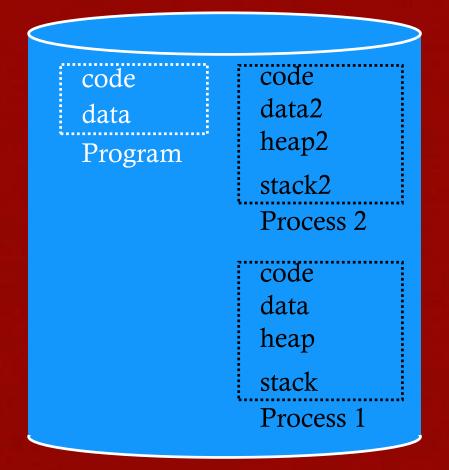
code data2 heap2

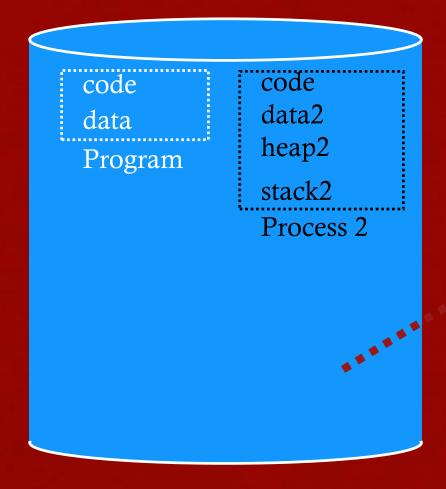
stack2

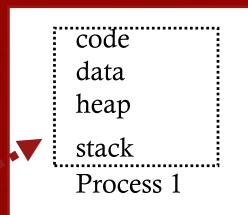
Process 2











code
data

Program

code
data2
heap2
stack2

Process 2

Memory

code data heap stack Process 1

PROBLEMS WITH TIME SHARING MEMORY

Problem: Ridiculously poor performance

Better Alternative: space sharing

• At same time, space of memory is divided across processes

Remainder of solutions all use space sharing

2) STATIC RELOCATION

- Idea: OS rewrites each program before loading it as a process in memory
- Each rewrite for different process uses different addresses and pointers
- Change jumps, loads of static data

0x1010: movl 0x8(%rbp), %edi 0x1013: addl \$0x3, %edi rewrite 0x1019: movl %edi, 0x8(%rbp)

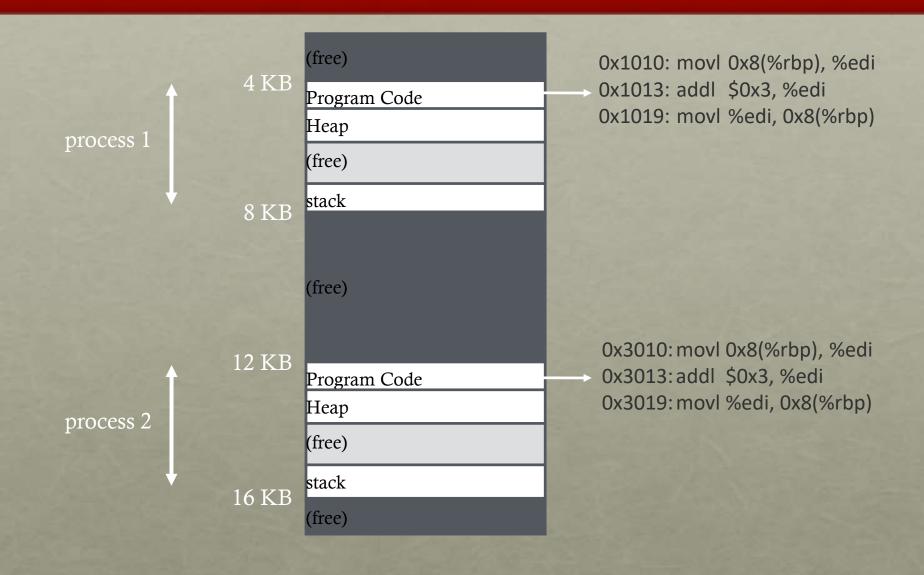
• 0x10: movl 0x8(%rbp), %edi

• 0x13: addl \$0x3, %edi

• 0x19: movl %edi, 0x8(%rbp)

0x3010: movl 0x8(%rbp), %edi rewrite 0x3013: addl \$0x3, %edi 0x3019: movl %edi, 0x8(%rbp)

STATIC: LAYOUT IN MEMORY



STATIC RELOCATION: DISADVANTAGES

No protection

- Process can destroy OS or other processes
- No privacy

Cannot move address space after it has been placed

May not be able to allocate new process

3) DYNAMIC RELOCATION

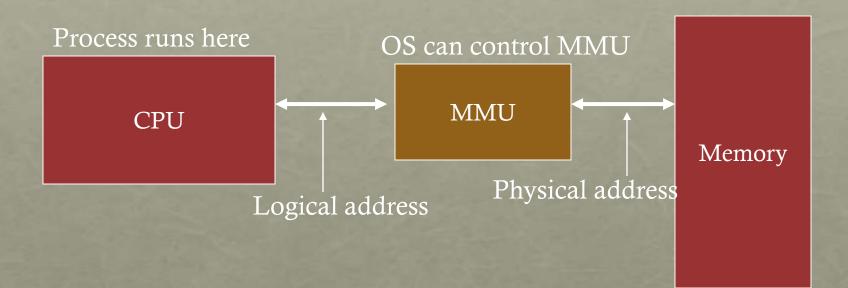
Goal: Protect processes from one another

Requires hardware support

Memory Management Unit (MMU)

MMU dynamically changes process address at every memory reference

- Process generates logical or virtual addresses (in their address space)
- Memory hardware uses physical or real addresses



HARDWARE SUPPORT FOR DYNAMIC RELOCATION

Two operating modes

- Privileged (protected, kernel) mode: OS runs
 - When enter OS (trap, system calls, interrupts, exceptions)
 - Allows certain instructions to be executed
 - Can manipulate contents of MMU
 - · Allows OS to access all of physical memory
- User mode: User processes run
 - · Perform translation of logical address to physical address

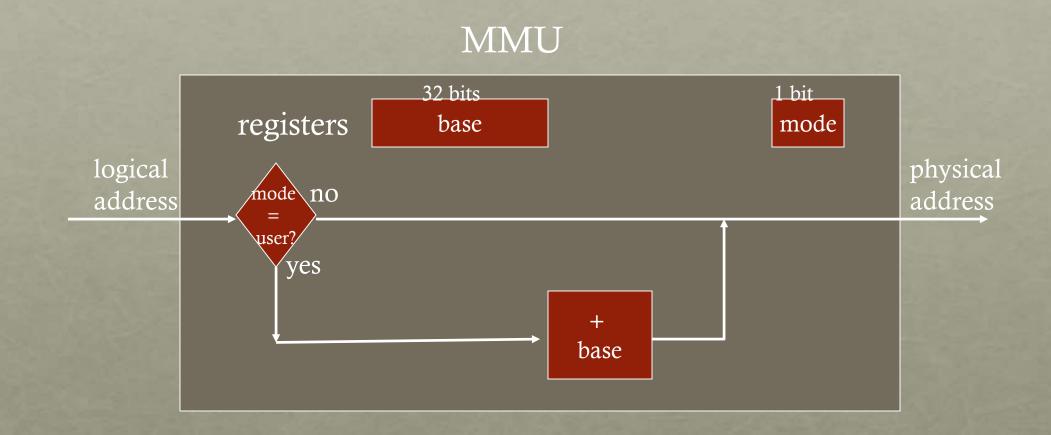
Minimal MMU contains base register for translation

base: start location for address space

IMPLEMENTATION OF DYNAMIC RELOCATION: BASE REG

Translation on every memory access of user process

MMU adds base register to logical address to form physical address

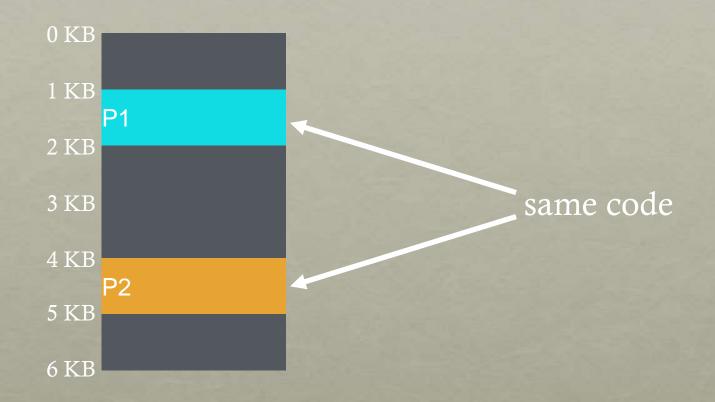


DYNAMIC RELOCATION WITH BASE REGISTER

Idea: translate virtual addresses to physical by adding a fixed offset each time.

Store offset in base register

Each process has different value in base register



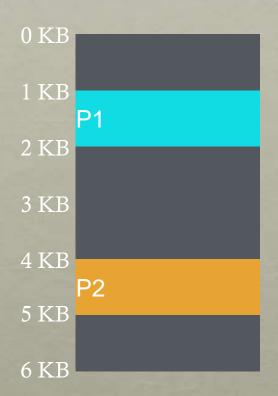
VISUAL EXAMPLE OF DYNAMIC RELOCATION: BASE REGISTER



P1 is running



P2 is running

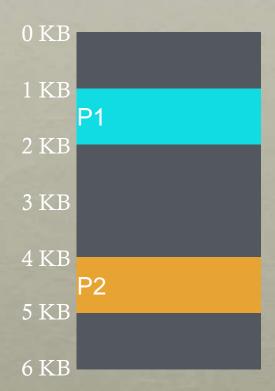


(Decimal notation)

Virtual	Physical
P1: load 100, R1	



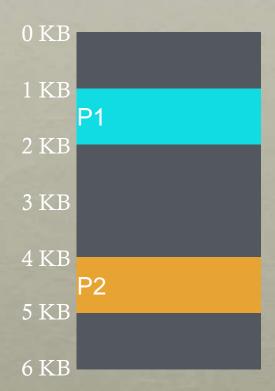
Virtual	Physical	
P1: load 100, R1	load 1124, R1	(1024 + 100)
	476.65	
	54 76 15 30 70 TS	



Virtual	Physical
P1: load 100, R1	load 1124, R1
P2: load 100, R1	
	SWITT BEATS



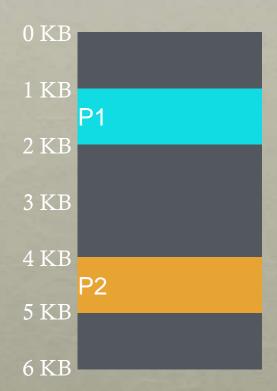
Virtual	Physical	
P1: load 100, R1	load 1124, R1	
P2: load 100, R1	load 4196, R1	(4096 + 100)
	2000000	
	K 320 33 33	



Virtual	Physical
P1: load 100, R1	load 1124, R1
P2: load 100, R1	load 4196, R1
P2: load 1000, R1	
	2 10 5000
	STATES OF THE PARTY.



Virtual	Physical
P1: load 100, R1	load 1124, R1
P2: load 100, R1	load 4196, R1
P2: load 1000, R1	load 5196, R1
	3866
	2 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
	CANEL PROPERTY



Virtual	Physical
P1: load 100, R1	load 1124, R1
P2: load 100, R1	load 4196, R1
P2: load 1000, R1	load 5196, R1
P1: load 100, R1	
	1800
	200000000000000000000000000000000000000
	ALCOHOLD TO THE PARTY OF THE PA

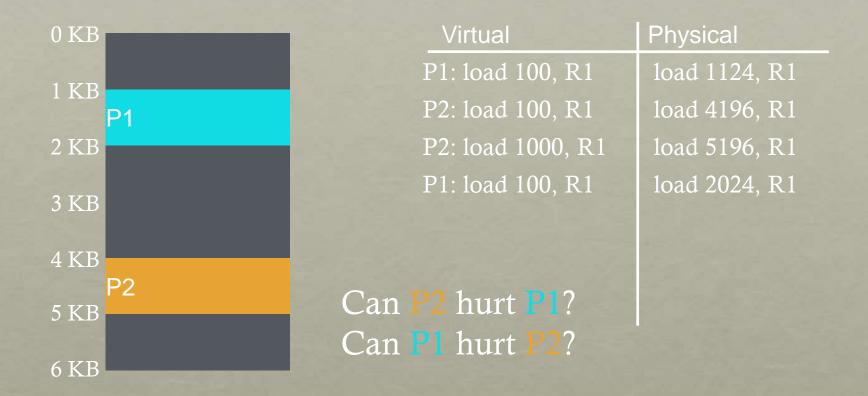


Virtual	Physical
P1: load 100, R1	load 1124, R1
P2: load 100, R1	load 4196, R1
P2: load 1000, R1	load 5196, R1
P1: load 1000, R1	load 2024, R1
	1808
	2 30 600
	576 S. S. S. S.

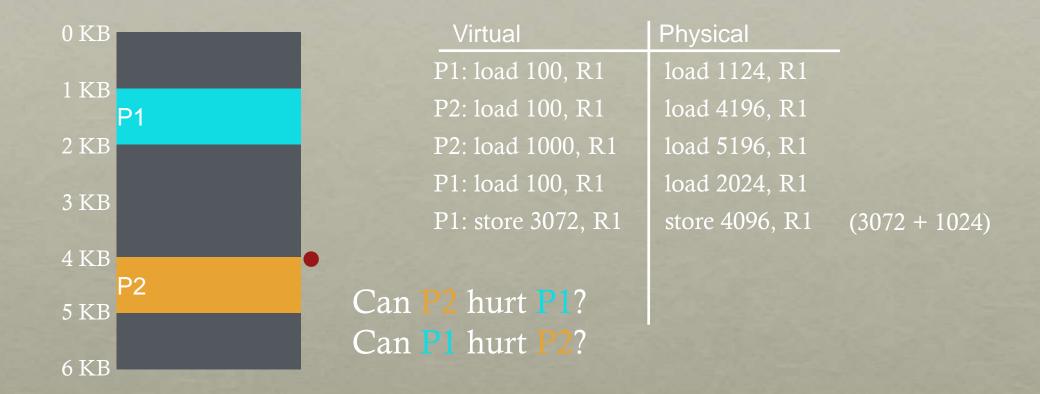
QUIZ: WHO CONTROLS THE BASE REGISTER?

What entity should do translation of addresses with base register? (1) process, (2) OS, or (3) HW

What entity should modify the base register? (1) process, (2) OS, or (3) HW



How well does dynamic relocation do with base register for protection?



How well does dynamic relocation do with base register for protection?

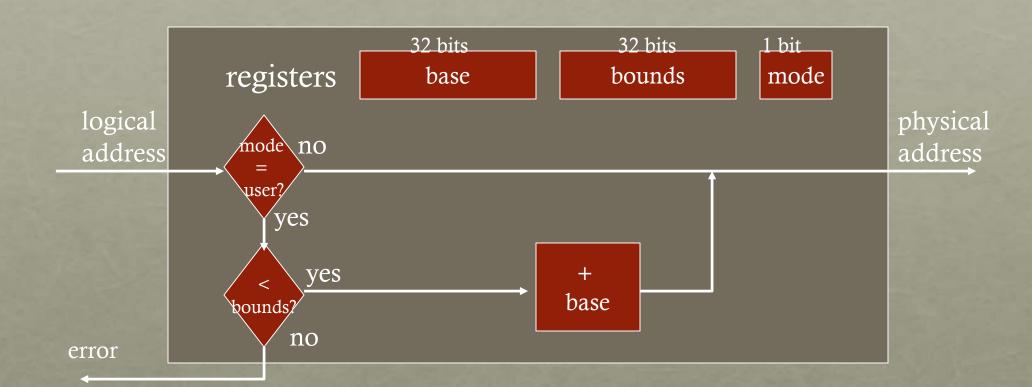
4) DYNAMIC WITH BASE+BOUNDS

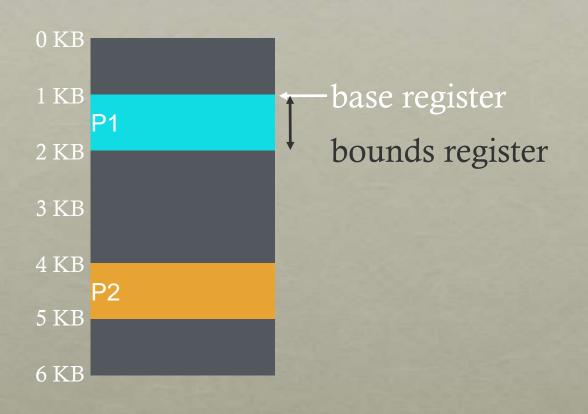
- Idea: limit the address space with a bounds register
- Base register: smallest physical addr (or starting location)
- Bounds register: size of this process's virtual address space
 - Sometimes defined as largest physical address (base + size)
- OS kills process if process loads/stores beyond bounds

IMPLEMENTATION OF BASE+BOUNDS

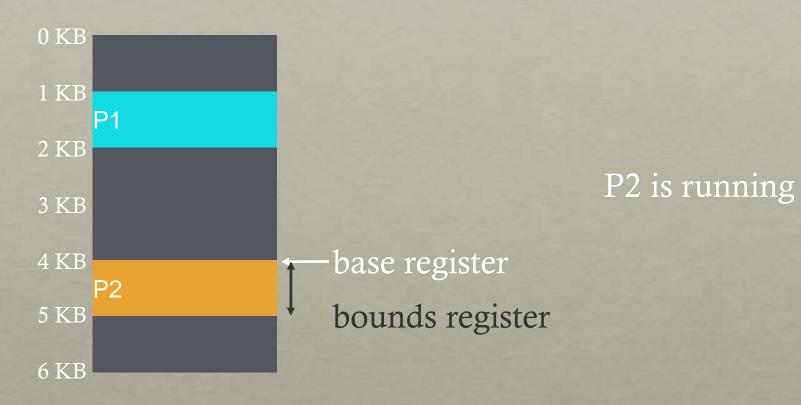
Translation on every memory access of user process

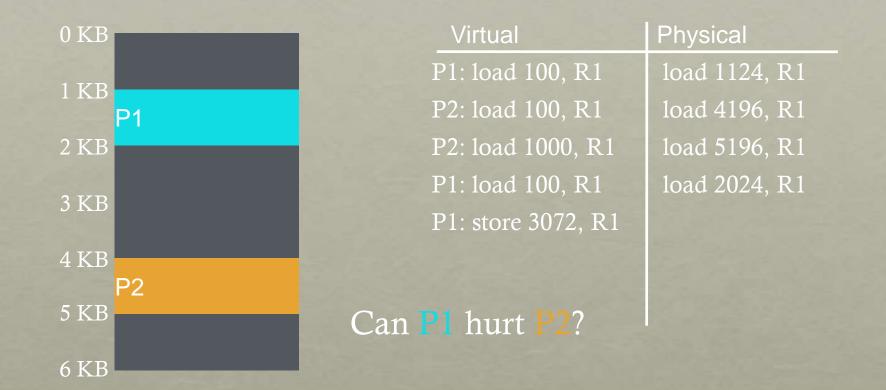
- MMU compares logical address to bounds register
 - if logical address is greater, then generate error
- MMU adds base register to logical address to form physical address

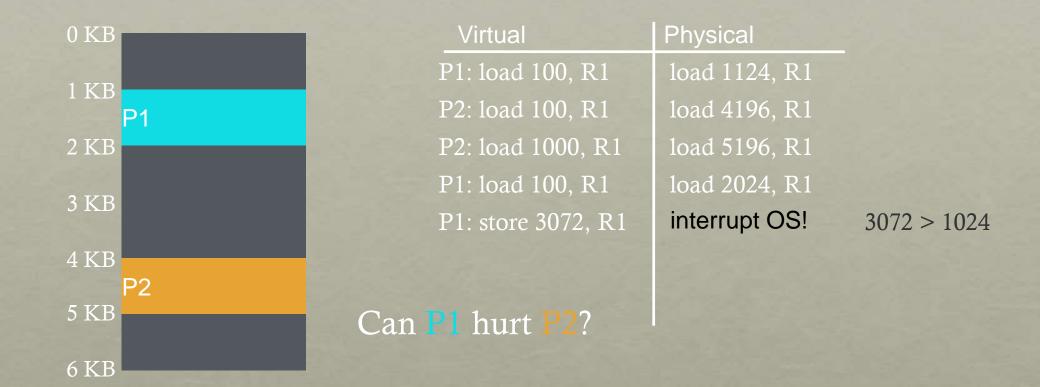


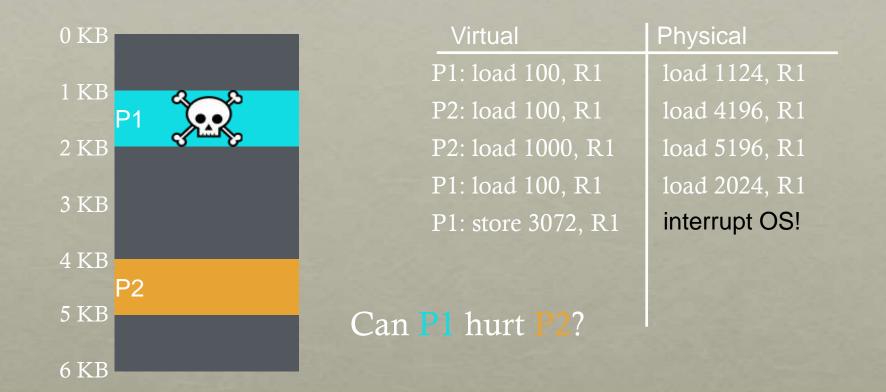


P1 is running









MANAGING PROCESSES WITH BASE AND BOUNDS

Context-switch

- Add base and bounds registers to PCB
- Steps
 - Change to privileged mode
 - Save base and bounds registers of old process
 - Load base and bounds registers of new process
 - Change to user mode and jump to new process

What if don't change base and bounds registers when switch?

Protection requirement

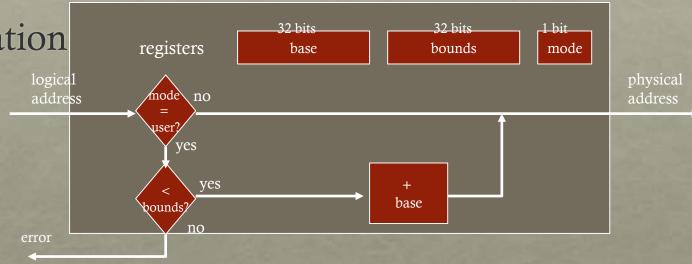
- User process cannot change base and bounds registers
- User process cannot change to privileged mode

BASE AND BOUNDS ADVANTAGES

Advantages

- Provides protection (both read and write) across address spaces
- Supports dynamic relocation
 - Can place process at different locations initially and also move address spaces

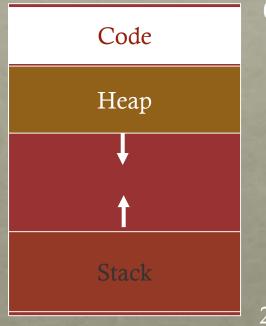
- Simple, inexpensive implementation
 - Few registers, little logic in MMU
- Fast
 - Add and compare in parallel



BASE AND BOUNDS DISADVANTAGES

Disadvantages

- Each process must be allocated contiguously in physical memory
 - Must allocate memory that may not be used by process
- No partial sharing: Cannot share limited parts of address space



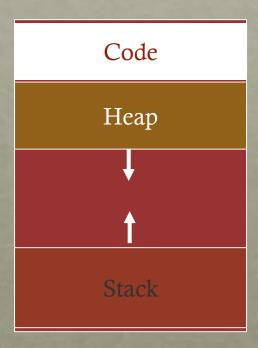
5) SEGMENTATION

Divide address space into logical segments

- Each segment corresponds to logical entity in address space
 - code, stack, heap

Each segment can independently:

- be placed separately in physical memory
- grow and shrink
- be protected (separate read/write/execute protection bits)



SEGMENTED ADDRESSING

Process now specifies segment and offset within segment

How does process designate a particular segment?

- Use part of logical address
 - Top bits of logical address select segment
 - Low bits of logical address select offset within segment

What if small address space, not enough bits?

- Implicitly by type of memory reference
- Special registers

SEGMENTATION IMPLEMENTATION

MMU contains Segment Table (per process)

- Each segment has own base and bounds, protection bits
- Example: 14 bit logical address, 4 segments; how many bits for segment? How many bits for offset?

Segment	Base	Bounds	R W
0	0x2000	0x6ff	1 0
1	0x0000	0x4ff	1 1
2	0x3000	Oxfff	1 1
3	0x0000	0x000	0 0

remember: 1 hex digit->4 bits

QUIZ: ADDRESS TRANSLATIONS WITH SEGMENTATION

MMU contains Segment Table (per process)

- Each segment has own base and bounds, protection bits
- Example: 14 bit logical address, 4 segments; how many bits for segment? How many bits for offset?

Segment	Base	Bounds	R W
0	0x2000	0x6ff	1 0
1	0x0000	0x4ff	1 1
2	0x3000	Oxfff	1 1
3	0x0000	0x000	0 0

remember: 1 hex digit->4 bits

Translate logical addresses (in hex) to physical addresses

 0×0240 :

0x1108:

0x265c:

 0×3002 :

VISUAL INTERPRETATION



Virtual (hex)
load 0x2010, R1

Physical

Segment numbers:

0: code+data

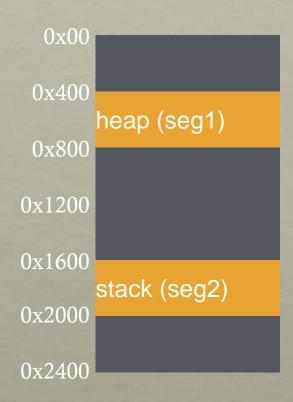
1: heap



Virtual (hex)	Physical
load 0x2010, R1	0x1600 + 0x010 = 0x1610
	THE REPORT OF THE PARTY OF THE
	100 61 600 1000

0: code+data

1: heap



Virtual (hex)	Physical
load 0x2010, R1	0x1600 + 0x010 = 0x1610
load 0x1010, R1	
	534 16T (F2 378 C.36)

0: code+data

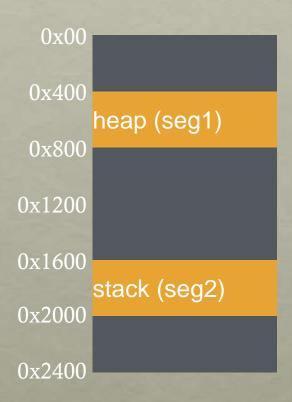
1: heap



Virtual (hex)	Physical
load 0x2010, R1	0x1600 + 0x010 = 0x1610
load 0x1010, R1	0x400 + 0x010 = 0x410
7. 10 10 10 10 10 10 10 10 10 10 10 10 10	

0: code+data

1: heap



Virtual	Physical
load 0x2010, R1	0x1600 + 0x010 = 0x1610
load 0x1010, R1	0x400 + 0x010 = 0x410
load 0x1100, R1	

0: code+data

1: heap



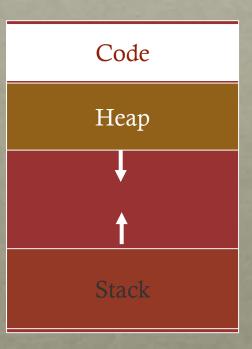
Virtual	Physical
load 0x2010, R1	0x1600 + 0x010 = 0x1610
load 0x1010, R1	0x400 + 0x010 = 0x410
load 0x1100, R1	0x400 + 0x100 = 0x500

0: code+data

1: heap

ADVANTAGES OF SEGMENTATION

- Enables sparse allocation of address space
 - Stack and heap can grow independently
 - Heap: If no data on free list, dynamic memory allocator requests more from OS (e.g., UNIX: malloc calls sbrk())
 - Stack: OS recognizes reference outside legal segment, extends stack implicitly
- Different protection for different segments
 - Read-only status for code
- Enables sharing of selected segments
- Supports dynamic relocation of each segment



DISADVANTAGES OF SEGMENTATION

Each segment must be allocated contiguously

May not have sufficient physical memory for large segments

Fix in next lecture with paging...

CONCLUSION

HW+OS work together to virtualize memory

• Give illusion of private address space to each process

Add MMU registers for base+bounds so translation is fast

• OS not involved with every address translation, only on context switch or errors

Dynamic relocation with segments is good building block

Next lecture: Solve fragmentation with paging